General Specifications

Supply Input......................... 10–40V 5A  Example: Digikey part 1776-1143-ND
Dimensions......................... 2.25" X 2.25" (57mm X 57mm) square, 1.0" (25mm) thick
Maximum Speed.................... >10,000,000 us/step (256 micro steps)
Operating Modes.................... PC controlled or standalone
PC Control.......................... Up to 16 controllers can be daisy-chained together.
Communications Protocol.......... USB, RS232, RS485, and CAN BUS. Direct USB, RS485, and CAN BUS connections built in. USB connector type is USB micro.
Control Protocol.................... Compatible with devices that use the Cavro DT or OEM protocol. Can use EZCommander™ Windows application or serial terminal program such as HyperTerminal to issue ASCII text-based commands.
Motor Compatibility............... Typically compatible with any stepper motor that is 3” or smaller (size 23 or smaller). Outputs can regulate to any motor voltage via software commands, e.g., 3V motor on 24V supply.
Mating Connectors ................ For power and motor, AMP MTA 100 series. Recommended tools: Digikey A9982; or (better) A1998 + A2031. (See Application Note 131021 for non-standard connector options.) For signal connections, HIROSE DF11 series.
Digital/Analog Interface......... Accepts opto-electronic or 16 mechanical switch inputs, or 16 ADC inputs. ADC inputs accurate to 7 bits; can be modified to 10 bit (contact AllMotion for details).
Signal Levels: <0.8V Vlow; >2V Vhigh (TTL compatible). Threshold set at 1.23V; can be changed via programming.
Optical switch specifications: Transistor optical switch with IC> 1 mA @ IF=20mA. Examples: Digikey QVA11134 or H21A1; Honeywell HOA1887-012 or HOA1870-33 (prewired); OPTEK OPB830W11 (prewired).
5V Output Current .................. 600mA total (power is available for encoders and sensors)
Encoder Interface ................ Max. freq. 4 MHz, 5V signals (3.3V upon request)
Operating Temperature .......... -20 to 85°C PCB copper temperature
Relative Humidity ............... 10% to 90% non condensing (operating and storage)

ANALOG/DIGITAL I/O CONNECTORS (4)
Mating connector: HIROSE DF11 Series 10 pin DF11-10DS-2C

<table>
<thead>
<tr>
<th>Pin</th>
<th>Function</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Switch 2 in / Digital 2G / Analog CH2</td>
<td>10k Ω pullup to 3.3V. Switch closure is to ground.</td>
</tr>
<tr>
<td>2</td>
<td>Switch 1 in / Digital 2H / Analog CH2</td>
<td>10k Ω pullup to 3.3V. Switch closure is to ground.</td>
</tr>
<tr>
<td>3</td>
<td>Opto 1 LED Drive / Drive 1 (TTL)</td>
<td>See Note 1.</td>
</tr>
<tr>
<td>4</td>
<td>Opto 1 in / Home / Lower Limit / Digital in 2G / Analog CH3</td>
<td>10k Ω pullup to 3.3V. Switch closure is to ground.</td>
</tr>
<tr>
<td>5</td>
<td>Opto 2 in / Upper Limit / Digital in 2S / Analog CH4</td>
<td>10k Ω pullup to 3.3V. Switch closure is to ground.</td>
</tr>
<tr>
<td>6</td>
<td>Ground</td>
<td>Common input ground</td>
</tr>
<tr>
<td>7</td>
<td>Ground</td>
<td>Common input ground</td>
</tr>
<tr>
<td>8</td>
<td>Opto 1 LED Drive / Drive 1 (TTL)</td>
<td>See Note 1.</td>
</tr>
<tr>
<td>9</td>
<td>Driver 3 (open drain) 0.5A</td>
<td>For solenoids, etc.</td>
</tr>
<tr>
<td>10</td>
<td>Driver 4 (open drain) 0.5A</td>
<td>For solenoids, etc.</td>
</tr>
</tbody>
</table>

ENCODER CONNECTORS (6)
Mating connector: HIROSE DF11 Series 8 pin DF11-8DS-2C

<table>
<thead>
<tr>
<th>Pin</th>
<th>Function</th>
<th>Notes</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Ground</td>
<td>Ground for encoder</td>
</tr>
<tr>
<td>2</td>
<td>Index</td>
<td>Input from encoder. High level must be &gt;4.5V (external pullups may be required).</td>
</tr>
<tr>
<td>3</td>
<td>Chan A</td>
<td>Input from encoder. See comment for Pin 2.</td>
</tr>
<tr>
<td>4</td>
<td>+5V (V+)</td>
<td>Power to encoder</td>
</tr>
<tr>
<td>5</td>
<td>Chan B / SPI_MISO</td>
<td>Input from encoder. See comment for Pin 2.</td>
</tr>
<tr>
<td>6</td>
<td>SPI_MOSI</td>
<td>Slave input from master (master output)</td>
</tr>
<tr>
<td>7</td>
<td>SPI_CLK</td>
<td>Serial clock from master</td>
</tr>
<tr>
<td>8</td>
<td>SPI_CS2</td>
<td>Chip select</td>
</tr>
</tbody>
</table>

RS485 CONNECTOR (EZ BUS)
Mating connector: HIROSE series 4 pin 22-30 GA, part DF11-4DS-2C

<table>
<thead>
<tr>
<th>Pin</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Ground</td>
</tr>
<tr>
<td>2</td>
<td>V+ (external supply)</td>
</tr>
<tr>
<td>3</td>
<td>RS485A</td>
</tr>
<tr>
<td>4</td>
<td>RS485B</td>
</tr>
</tbody>
</table>

MOTOR POWER CONNECTORS (4)
Mating connector: AMP MTA 100 Series 4 pin, 22 GA, part 3-643813-2 Digikey part A31363-ND

<table>
<thead>
<tr>
<th>Pin</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>V+ (external supply)</td>
</tr>
<tr>
<td>2</td>
<td>GROUND</td>
</tr>
</tbody>
</table>

MOTOR OUTPUT CONNECTORS (4)
Mating connector: AMP MTA 100 Series 4 pin, 22 GA, part 3-643813-4 Digikey part A31108-ND

<table>
<thead>
<tr>
<th>Pin</th>
<th>Function</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Phase A+</td>
</tr>
<tr>
<td>2</td>
<td>Phase A-</td>
</tr>
<tr>
<td>3</td>
<td>Phase B+</td>
</tr>
<tr>
<td>4</td>
<td>Phase B-</td>
</tr>
</tbody>
</table>

Note 1: Each LED sensor input includes a series 200 Ω resistor to 5V. Resistor can be removed for sensors needing direct access to 5V. Max current draw is <200mA.
Note 2: The USB connector type is USB micro.
Note 3: For CAN BUS connections, see other side.
EZQuadHRStepper
Intelligent 4-axis Stepper Controller/Driver
with Quad Encoder feedback

Mechanical Specifications

Outside connector pin numbering reads clockwise except where otherwise noted.

CAN BUS CONNECTOR
1 CAN HIGH BUS
2 CAN LOW BUS
3 SIGNAL GROUND
4 RESERVED

ENCODER CONNECTOR
1 GROUND
2 INDEX
3 CHANNEL A
4 +5V
5 CHANNEL B/ SPI_MISO
6 SPI_MOSI
7 SPI_CLK
8 SPI_CS2

ANALOG_DIGITAL I/O CONNECTOR
1 SWITCH 2 IN / DIGITAL 2^0 / ANALOG CH2
2 SWITCH 2 IN / DIGITAL 2^1 / ANALOG CH2
3 OPTO 1 LED DRIVE / DRIVE 1 (TTL)
4 OPTO 1 / HOME / LOWER LIMIT / DIGITAL IN 2^2 / ANALOG CH3
5 OPTO 2 / UPPER LIMIT / DIGITAL IN 2^3 / ANALOG CH4
6 GND
7 GND
8 OPTO 1 LED DRIVE / DRIVE 1 (TTL)
9 DRIVER 3 (OPEN DRAIN) 0.5A
10 DRIVER 4 (OPEN DRAIN) 0.5A

TYPICAL CONNECTIONS PER CHANNEL

STEP MOTORS
PHASE A+
PHASE A−
PHASE B+
PHASE B−

See wiring diagram for color codes

Key Features

- Full-featured 4-axis position controller with power drivers
- Accepts four encoders plus two auxiliary encoders
- Four independent 2A stepper motor drives
- 10V to 40V 2A operation
- Pre-wired for opto-switch and limit inputs
- Halt/branch on ADC value
- RS232, RS485, USB, or CAN BUS based communications
- Direct USB, RS485, and CAN bus connection built in
- Industry standard communications protocol
- Single 4-wire bus links up to 16 AllMotion products
- Standalone operation with no connection to a PC
- 16 analog inputs (ADC) and 16 power on/off drivers
- Switch-selectable device address
- On-board EEPROM for user program storage
- Homes to opto or switch closure with one command
- Independent parameters for all axes (acceleration, velocity, currents, etc.)
- Fully programmable acceleration ramps and speeds
- Execution halt/branch pending switch closure

See EZQUAD HR STEPPER wiring diagram (on website) and/or user guide for application details.

Ordering Information

Name | Order Number
--- | ---
EZQUAD 4-Axis HR Stepper Controller/Driver EZQUADHRSTEPPER | RS232 to RS485 Converter (option)................................RS485
RoHs-compliant