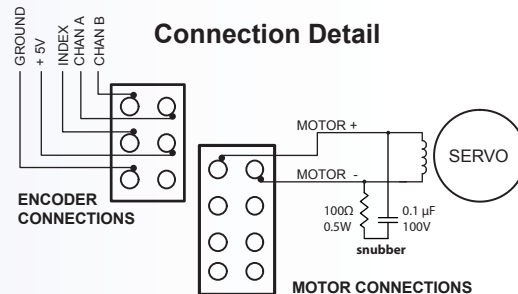
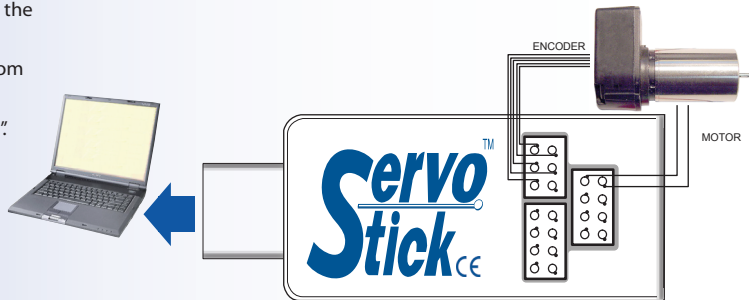


Get your **EZServo** going!

1. Download and install EZ Commander software from the AllMotion® website: www.allmotion.com.
2. Download and install the appropriate USB drivers from the AllMotion® website Support page.
3. In EZ Commander, click "Settings," then "Rescan Ports." Note available com ports. Click "OK."
4. Plug ServoStick™ into the computer.
5. In EZ Commander, click "Settings," then "Rescan ports." A new com port should appear.
6. Select the new com port. Click "OK."
7. Unplug ServoStick™.
8. Connect servo motor and encoder as shown while ServoStick™ is unplugged. Preferably, an RC snubber (as shown) should be placed near motor to suppress brush arcing.
9. Plug ServoStick™ back into the computer.
10. In EZ Commander, issue the command "/1P00R". This tells the motor to turn 1000 encoder counts, then and stop and hold position. Confirm by reading back encoder with command "/1?8".
If motor does not hold position, swap encoder A and B channel connections and try again.
11. Download full documentation from the AllMotion® website.

Starter Kit Instructions ServoStick™ Controller + Driver



CAUTION!

Do not connect or disconnect motor with ServoStick™ plugged in.

Unplugging of or intermittent connection to an inductive load creates a high voltage/spark, which will damage the driver.

ALLMOTION

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